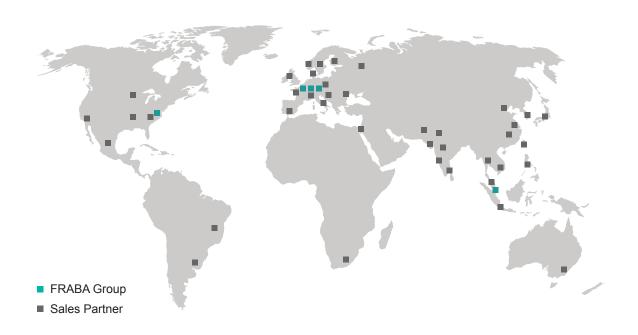


# POSITION SENSORS



## **GLOBAL PRESENCE**



America	Asia	Europe
FRABA Inc.	FRABA Pte. Ltd.	POSITAL GmbH
Hamilton, NJ, USA	Singapore	Cologne, Germany

R&D Center	Manufacturing	Holding
Centitech GmbH	Consitics Sp. z o.o.	FRABA N.V.
Aachen, Germany	Slubice, Poland	Heerlen, The Netherlands

## Sales Partners Present in

Argentina	Indonesia	Slovakia
Australia	Israel	South Africa
Austria	Italy	South Korea
Belarus	Japan	Spain
Brazil	Malaysia	Sweden
Canada	Mexico	Switzerland
China	Netherlands, The	Taiwan
Czech Republic	Norway	Thailand
Denmark	Pakistan	U.K.
Finland	Philippines	USA
France	Poland	Ukraine
Germany	Russia	
India	Singapore	

Please visit our website for partner contacts in all countries as the list is constantly growing.

#### **GLOBAL PRESENCE**



#### **FRABA Group**

FRABA is a group of enterprises focused on providing advanced products for the motion control and industrial automation markets. POSITAL has been a leading manufacturer of absolute rotary encoders for over 40 years and the last years has expanded its business to inclination and non-contact length and velocity sensors. Other FRABA Group subsidiaries include VITECTOR which focuses on protection sensors to guard doors and production machine covers.

#### History

The company was founded by Franz Baumgartner in Cologne in 1918. Until the 1960s, FRABA's main product was mechanical relays. This business was supported by the company's systems engineering division, which was responsible for over 13,000 machine control systems. FRABA developed one of the first absolute rotary encoders in 1973. Today, FRABA companies specialize in innovative products that use advanced technologies to deliver exceptional performance and value.





#### **Service**

Absolute rotary encoders are sophisticated devices that can help solve a wide range of technical problems. However, realizing the full potential of these products may require specialized knowledge when selecting the device configuration and programming the operating parameters. To ensure that customers get what they need, POSITAL's development engineers in Germany, the US and Asia have direct responsibility for customer support. In addition, a growing global network of sales partners is providing expert guidance with knowledge about the local requirements.

#### **Production**

POSITAL products are manufactured in advanced production facilities. The computer-guided semi-automated production system tracks each device from order, through assembly and testing, to final delivery. Even with thousands of unique configurations available, standard products are ready to ship within five working days of receiving an order.



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## Disclaimer

Glossary

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Version 20130426

#### **PRODUCTS**



#### Rotary Encoders - IXARC

Motion control applications – ranging from factory automation to mobile machinery – require precise, real-time information about the physical location of mechanical equipment. The IXARC line of absolute rotary encoders can provide precise and unambiguous measurements of the angular positions of joints, drive shafts, pulleys, etc. in real time. This makes absolute rotary encoders an ideal way of linking mechanical components to an electronic control system.

## Inclinometers - TILTIX

Accurate measurement of the degree of tilt or inclination can be very important for motion control systems or to ensure safety. The TILTIX line of inclinometers offers an easy and efficient way of monitoring spatial orientation without the need for mechanical linkages. This feature, plus the durable packaging of many inclinometers means that these devices can be placed almost anywhere – a real advantage for design engineers!





#### **Linear Sensors - LINARIX**

Many applications require linear motion to be monitored for system control or to ensure safety. The LINARIX line of draw wire sensors is best suited for such applications and provides a diverse selection for the customer. We offer a wide range of measurement lengths ranging from 1 m to 15 m and also provide position output in almost all available industrial interfaces both analog and digital. The draw wire sensors from POSITAL provide extremely precise measurements because of the inherent accuracy of the encoders and the rugged construction ensures reliable performance even under extreme conditions.

#### Accessories

POSITAL offers a wide variety of accessories that simplify the installation process of our sensors. Connectors and cable assemblies of different sizes, couplings, adapter flanges and clamp discs for exact fitting as well as interface modules and displays are a few of the available accessories.



#### APPLICATIONS TOUGH POSITION



#### **Drilling**

Drill rigs, bucket wheel excavators and mobile hammering machines have multiple axis and joints between their arms. Precise positioning information between the arms is necessary in order to identify the exact position of the tip of the arm and have a controlled movement of the arm, in an application where safety is the prime concern. Moreover, maintaining a constant drill angle is imperative for high performance. Moving away from a given angle can be dangerous and costly to the project. Typically in such applications there are strong vibrations. IXARC encoders and TILTIX inclinometers are available with heavy duty housing and very high protection class. Sometimes where flammable gases are present, explosion proof encoders can also be used.

#### Cranes

Cranes and other loading equipments are required to operate safely and precisely. Positioning is of pri-

me importance here, and a lot of time redundancy is used to ensure that no errors are being made. The IXARC SIL-2 encoders fit perfectly in this application. The LINARIX magnetic sensors used for height measurement; come in an extremely small package and are highly tolerant to condensation, shock and vibration.

#### **Concrete Pumps**

Concrete pumps have a large number of joints and axis of rotation. They have to feed fresh concrete to high-rise construction sites, often over high obstacles. IXARC rotary encoders are being used directly on the rotational joint providing active damping of the multiple arms. Concrete pumps have to handle very tough environments. On top of that these machines are cleaned with high pressure steam. By avoiding direct coupling to a shaft, a fully enclosed measuring device like a TILTIX inclinometer will stand up to these rough conditions.





#### APPLICATIONS TOUGH POSITION



#### Wind Energy

IXARC heavy duty absolute encoders guarantee precise angle measurement for the pitch control system that dynamically controls the angle of the rotor blades. Encoders with a high resolution are a great choice for positioning the nacelle depending on the wind direction.

#### Solar Energy

For both photovoltaic systems and solar thermal power plants (parabolic), solar tracking systems increase energy efficiency by optimizing the orientation of the solar collectors with respect to the sun. Single-axis solar tracking systems typically follow the sun as it travels east to west across the sky, while two axis systems also adjust the vertical orientation of the collectors with the help of compact and accurate IXARC encoders and TILTIX inclinometers.

#### **Dams and Canals**

In several dams for hydro energy generation a precise positioning of the flow gates is required to control the amount and speed of water flowing through. These gates both open in an angular fashion or vertically and use the TILTIX inclinometers or LINARIX linear sensors respectively. The standard analog interfaces make the control system very simple.

Canal gates used for irrigation as well as transportation needs to be precisely positioned in order to control the amount of water in the canals. Moreover the canals are spread over vast areas and these gates are powered at times with solar energy due to vast distances. IXARC absolute multiturn encoders are used for gate positioning as they do not need to be powered all the time to remember their position.





#### APPLICATIONS INDUSTRIAL GRADE



#### **Packaging and Pharma Machines**

Packaging machines have multiple processes like form filling and sealing, palletizing, pick and place, cartooning and cardboard folding where absolute position encoders are used. Normally these machines have a lot of sensors the IXARC absolute field bus encoders help in reducing cabling and system costs.

Pharma machines need to have a very precise positioning of bottles for filling it with the right amount and correct batch of medicine. IXARC absolute encoders provide good track and traceability during power failures for this time critical industry.

## **Textile and Plastic Manufacturing Machines**

Textile and Plastic Manufacturing is highly process driven with various stages along multiple drive rollers. The material manufactured is changed periodically and constant adjustments need to be made in the roll positioning as well as positioning of various



nozzles controlling the production process. IXARC absolute encoders and LINARIX linear sensors are used for these applications.

#### **Food and Beverage Machines**

Bottling plants are becoming faster by the day for feeding the growing global demands. Each of these bottles must be filled to the right level and labelled correctly. IXARC encoders are used to ensure this precise positioning of these bottles.

Increased food prices are forcing manufactures to reduce wastage. These manufactures have to comply with strict laws and hence need to pack and process these goods at the right time and quickly. IXARC encoders and LINARIX linear sensors help achieve this efficiency. POSITAL offers a wide range of non-corrosive stainless steel products with various standard industrial interfaces





#### APPLICATIONS INDUSTRIAL GRADE



#### Scissor Lifts and Aerial work Platforms

Each Scissor lift needs constant monitoring of the tilt due to safety reasons. The height of the lift also needs to be precisely determined. TILTIX inclinometers and LINARIX linear sensors are perfect for such applications. IXARC absolute encoders help measure the position of the Aerial work platform with respect to a ground reference.

#### **Forklifts and Automated Guided Vehicles**

In forklifts and AGV's safety is of utmost importance as these vehicles carry load from one point to another. Monitoring the tilt as well as the height of the forks is necessary and the TILTIX inclinometers and LINARIX linear sensors help achieving this.

## **Automatic Storage Retrieval System**

Increasing warehouse and labor costs make the use of automatic storage and retrieval systems economical. The IXARC absolute encoders and LINARIX linear sensors are used in these systems to give the

position of the trays with respect to the vertical racks where the goods are placed.

#### **Overhead Conveyors**

Assembly lines for automotive production have dedicated work stations for different processes. The vehicle chassis is moved through a series of such work stations using overhead conveyors. A precise position of the overhead conveyors is needed in an automated assembly line with robots. IXARC absolute encoders help achieve this level of precision.

#### **Baggage Handling**

Due to stringent security requirements all airline baggage need to be screened and distributed in a fool proof manner at each airport. A labyrinth of conveyors helps sort these in a correct fashion. IXARC absolute bus encoders help track the position of multiple baggage conveyors. The reduced wiring and programmability reduces the system cost to a great extent.





#### APPLICATIONS COST EFFICIENT



#### **Health Care**

Modern devices used in the Healthcare industry demand advanced technology for precise positioning. With TILTIX inclinometers you can keep track of the exact angle of your CT scanner with no extra equipment needed. Our compact inclinometers always provide an accurate measurement output and guarantee a long life span. LINARIX linear sensors can offer a solution for determining length and height measurements of your CT or operating tables. For applications that need position monitoring from several directions, such as fluoroscopy or radiography tables, Surgical C-arms or Navigation-Mobile C-arms, the IXARC absolute rotary encoders are the right solution.

#### **Elevators**

Elevator car units need to be accurately positioned with respect to each floor of a building. IXARC absolute encoders help provide this information without the need of a ground reference. During power failures the elevator car shall always know where it is positioned. IXARC encoders are available with the CANopen Lift protocol fulfilling the high safety standards of this industry. Cost efficient LINARIX linear sensors are used for door positioning.



## ABSOLUTE VS INCREMENTAL ENCODERS



Positioning tasks require precise position values to monitor or control motion activity. In many applications position sensing is done using rotary encoders, also called shaft encoders or simply encoders. These sensors transform a mechanical angular position of a shaft or axle into an electronic signal that can be processed by a control system.

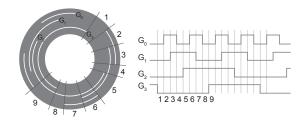
## **Absolute Rotary Encoders**

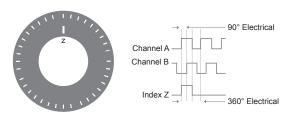
Absolute rotary encoders are capable of providing unique position values from the moment they are switched on as well as immediately after a power loss. This is accomplished by scanning the position of a coded material. All positions in these systems correspond to a fixed code. Even movements that occur while the system is without power are translated into accurate position values at once when the encoder is powered up again.



## **Incremental Rotary Encoders**

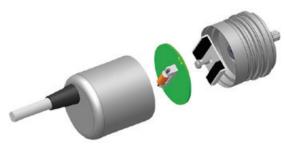
Incremental encoders measure angle values by counting a material with a periodic pattern, starting from an arbitrary origin. This measuring method does not inherently render absolute positions for a measured signal. Initial homing to a reference point is therefore inevitable in all positioning tasks, both upon start up of the control system and whenever power to the encoder has been interrupted.





#### TECHNOLOGY MAGNETIC ENCODER - IXARC





#### **Magnetic Measurement Principles**

Magnetic rotary encoders determine angular position using magnetic field sensor technology. A permanent magnet (a) fixed to the encoder's shaft creates a magnetic field (b) that is sampled by a sensor (c) that generates a unique absolute position reading.

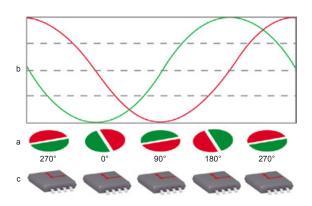
#### **Multiturn Innovation**

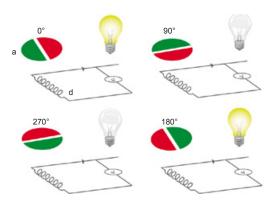
POSITAL's IXARC multiturn magnetic rotary encoders use an innovative technology to keep track of the number of rotations that the encoder has experienced, even if the rotations occur when there is no system power. To accomplish this, the encoders generate electrical energy from the rotation of the encoder shaft. The technology is based on the 'Wiegand effect': when a permanent magnet (a) on the encoder shaft rotates through a certain angle, the magnetic polarity in a 'Wiegand wire' suddenly changes, inducing a brief voltage spike in a coil (d)

surrounding the wire. This pulse both marks a rotation of the shaft and powers the electronic circuitry that records the event. The Wiegand effect occurs reliably even with very slow rotations and requires no backup batteries.

#### **Advantages of Magnetic Encoders**

Magnetic encoders are robust, durable and compact. Their battery and gearless construction makes them mechanically simple and cost efficient as compared to optical encoders. Their compact dimensions mean that they can be used in applications with very limited installation space.





## TECHNOLOGY OPTICAL ENCODER - IXARC



#### **Measuring Principles**

A key component of optical rotary encoders is a code disk (a) mounted on the encoder shaft (b). This is a disk made of transparent material that carries a concentric pattern of transparent and opaque areas. Infrared light from an LED (c) shines through the code disk, onto an array of photoreceptors (d). As the shaft turns, a unique combination of photoreceptors are illuminated or blocked from light by the pattern on the disk. For multiturn models, there is an additional set of code discs arranged in a gear train (e). As the main encoder shaft rotates, these discs are geared together to turn like the wheels of an odometer. The rotational position of each disc is monitored optically and the output is a count of the net number of rotations of the encoder shaft.

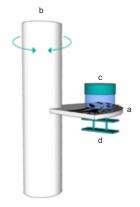


#### **Functionality**

POSITAL's IXARC optical absolute rotary encoders use highly integrated Opto-ASICs, providing a resolution up to 16 bits (65,536 steps) per turn, along with incremental signals. For multiturn models, the measuring range is extended by the mechanically geared code disks to as many as 16,384 (2<sup>14</sup>) revolutions.

#### **Advantages of Optical Encoders**

Optical encoders provide very high resolution and accuracy along with excellent dynamic response and are suitable for use in areas with high magnetic fields. As well, since the rotation of the code discs is an entirely mechanical process, there is no risk of these devices losing track of their absolute position due to a temporary loss of instrument power. No backup batteries are required!





## **Heavy Duty Encoders with Analog and SSI Interfaces**



Highlights	Stainless Steel SSI Encoder with 300N Shaft Load	Cost Efficient IP69K SSI Encoder	Stainless Steel Analog Encoder with 300N Shaft Load	Cost Efficient IP69K Analog Encoder
Protection Class	IP69K	IP69K	IP69K	IP69K
Communication Interface	SSI	SSI	Analog Voltage, Current	Analog Voltage, Current
Technology	Magnetic	Magnetic	Magnetic	Magnetic
Revolutions (Turns)	Up to 16 bit	Up to 16 bit	Up to 32768 turns	Up to 32768 turns
Resolution	Up to 14 bit	Up to 14 bit	Total 12 bit	Total 12 bit
Accuracy /	±0.35°	±0.35°	±0.35°/	±0.35°/
Linearity			0.05 %	0.05 %
Flange Size in mm [in]	42 [1.65]	36 [1.42]	42 [1.65]	36 [1.42]
Flange Type	Synchro	Synchro	Synchro	Synchro
Shaft Diameters in mm [in]	10 [0.39]	10 [0.39]	10 [0.39]	10 [0.39]
Material Flange / Housing	Stainless Steel (V2A)	Aluminum / Steel	Stainless Steel (V2A)	Aluminum / Steel
RPM /	Max. 6000 /	Max. 6000 /	Max. 6000 /	Max. 6000 /
Radial Shaft Load in N	300	180	300	180
Shock /	300 g /	300 g /	300 g /	300 g /
Vibration <sup>1</sup>	30 g	30 g	30 g	30 g
Temperature	-40 to +85	-40 to +85	-40 to +85	-40 to +85
in°C [°F]/	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /
Humidity	98 %	98 %	98 %	98 %
Connection	Connector / Cable Gland	Connector / Cable Gland	Connector / Cable Gland	Connector / Cable Gland
Supply Voltage	4.5 to 30 V	4.5 to 30 V	12 to 30 V	12 to 30 V
Certificate	UL, CE	UL, CE	UL, CE	UL, CE
	MCD- SG10G	,	MCD- AG10G	MCD- AD10D
Туре	IVIOD- 30100	MCD- SD10D	IVIOD- AG 10G	MICD- AD IUD

<sup>1</sup> Based on (EN 60068-2-27) / (EN 60068-2-6)

## **Heavy Duty Encoders with Bus Interfaces**







Highlights	Cost Efficient	High Precision	Stainless Steel
	IP69K	CAN Encoder	CAN Encoder
	CAN Encoder	with IP68 Rating	with 300 N Shaft Load
Protection Class	IP69K	IP68	IP69K
Communication Interface	DeviceNet, CANopen	DeviceNet, CANopen	DeviceNet, CANopen
	(DS406), CANopen Lift	(DS406), CANopen Lift	(DS406), CANopen Lift
	(DSP417), SAE J1939	(DSP417), SAE J1939	(DSP417), SAE J1939
Technology	Magnetic	Optical	Magnetic
Revolutions	Up to 16 bit	Up to 14 bit	Up to 16 bit
Resolution	Up to 14 bit	Up to 16 bit	Up to 14 bit
Accuracy	±0.35°	±0.022°	±0.35°
Flange Size in mm [in]	36 [1.42]	58 [2.28]	42 [1.65]
Flange Type	Synchro	Synchro, Clamp,	Synchro
		Blind Hollow	
Shaft Diameters in mm [in]	10 [0.39]	Shaft 10 [0.39]	10 [0.39]
		Hub from 6 to 15	
		[0.24 to 0.59]	
Material Flange /	Aluminum /	Aluminum /	Stainless Steel (V2A)
Housing	Steel	Aluminum	
RPM /	Max. 6000 /	Max. 6000 /	Max. 6000 /
Radial Shaft Load in N	180	110	300
Shock /	300 g /	100 g /	300 g /
Vibration <sup>1</sup>	30 g	10 g	30 g
Temperature	-40 to +85	-40 to +85	-40 to +85
in °C [°F] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /
Humidity	98 %	98 %	98 %
Connection	Connector /	Connector /	Connector /
	Cable Gland	Cable Gland	Cable Gland
Supply Voltage	4.5 to 30 V	4.5 to 30 V	4.5 to 30 V
Certificate	UL, CE	UL, CE	UL, CE
Туре	MCD- C/DD10D	OCD- C/D	MCD- C/DH

<sup>1</sup> Based on (EN 60068-2-27) / (EN 60068-2-6)

Please refer to the product finder on our website for all possible combinations.

## Industrial Encoders with Analog, SSI, Bit Parallel and Incremental Interfaces



Max. 12000 /

110

100 g /

-40 to +85

[-40 to +185] /

Connector /

Cable Gland

4.5 to 30 V

UL, CE

MCD-..

10 g

98 %

Max. 12000 /

110

100 g /

-40 to +85

[-40 to +185] /

Connector /

Cable Gland

4.5 to 30 V

UL, CE

OCD-..

10 g

98 %

Max. 12000 /

110

100 g /

-40 to +85

[-40 to +185] /

Connector /

Cable Gland

12 to 30 V

UL, CE

MCD-..

10 g

98 %

1 Based on (EN 60068-2-27) / (EN 60068-2-6)

Max. 12000 /

110

100 g /

-40 to +85

[-40 to +185] /

Connector /

Cable Gland

4.5 to 30 V

UL, CE

OCD-..

10 g

98 %

Please refer to the product finder on our website for all possible combinations.

Max. 12000 /

110

100 g /

-40 to +85

[-40 to +185] /

Connector /

Cable Gland

4.5 to 30 V

UL, CE

OCD-..

10 g

98 %

RPM /

Radial Shaft

Load in N

Vibration<sup>1</sup>

Temperature

in °C [°F] /

Connection

Certificate

Type

Supply Voltage

Humidity

Shock /

## **Industrial Encoders with Bus Interfaces**











Highlights	Encoder with PROFIBUS Interface	Precise Encoder with CAN Bus Interface	Compact Encoder with CAN Bus Interface	Precise Encoder with DeviceNet Interface	Compact Encoder with DeviceNet Interface
Protection Class	Up to IP67	Up to IP67	Up to IP65	Up to IP67	Up to IP65
Communication	PROFIBUS DPV0/	CANopen (DS406)	CANopen (DS406)	DeviceNet	DeviceNet
Interface	DPV1/DPV2	CANopen Lift (DSP417)	CANopen Lift (DSP417)		
Technology	Optical	Optical	Magnetic	Optical	Magnetic
Revolutions	Up to 14 bit	Up to 14 bit	Up to 16 bit	Up to 14 bit	Up to 16 bit
Resolution	Up to 16 bit	Up to 16 bit	Up to 14 bit	Up to 16 bit	Up to 14 bit
Accuracy	±0.022°	±0.022°	±0.35°	±0.022°	±0.35°
Flange Size in	58 [2.28]	58 [2.28]	58 [2.28]	58 [2.28]	36 [1.42]
mm [in]					58 [2.28]
Flange Type	Clamp, Synchro, Blind Hollow	All	Clamp, Synchro, Blind Hollow	All	Clamp, Synchro, Blind Hollow
Shaft Diameters	From 6 to 15	From 6 to 15	From 6 to 15	From 6 to 15	From 6 to 15
in mm [in]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]
Material Flange /	Aluminum or	Aluminum or	Aluminum /	Aluminum or	Aluminum /
Housing	Stainless Steel /	Stainless Steel/ Steel	Steel	Stainless Steel /	Steel
RPM /	Max. 12000 /	Max. 12000 /	Max. 12000 /	Max. 12000 /	Max. 12000 /
Radial Shaft	Max. 120007	110	110	110	110
Load in N	110	110	110	110	110
Shock /	100 g /	100 g /	100 g /	100 g /	100 g /
Vibration <sup>1</sup>	10 g	10 g	10 g	10 g	10 g
Temperature	-40 to +85	-40 to +85	-40 to +85	-40 to +85	-40 to +85
in °C [°F] / Humidity	[-40 to +185] / 98 %	[-40 to +185] / 98 %	[-40 to +185] / 98 %	[-40 to +185] / 98 %	[-40 to +185] / 98 %
Connection	Connector /	Connector /	Connector /	Connector /	Connector /
	Connection Cap	Connection Cap	Connection Cap	Connection Cap	Connection Cap
Supply Voltage	10 to 30 V	10 to 30 V	10 to 30 V	10 to 30 V	10 to 30 V
Certificate	UL, CE	UL, CE	UL, CE	UL, CE	UL, CE
Туре	OCD	OCD	MCD	OCD	MCD

<sup>1</sup> Based on (EN 60068-2-27) / (EN 60068-2-6)

Please refer to the product finder on our website for all possible combinations.

## **Industrial Encoders with Ethernet Interfaces**











Highlights	Precise Encoder with EtherNet/IP	Absolute PROFINET Encoder	Precise Encoder with Modbus / TCP	Encoder with ETHERNET POWERLINK	Encoder with EtherCAT
Protection Class	Up to IP67	Up to IP67	Up to IP67	Up to IP67	Up to IP67
Communication Interface	EtherNet/IP	PROFINET	Modbus / TCP	ETHERNET POWERLINK	EtherCAT
Technology	Optical	Optical	Optical	Optical	Optical
Revolutions	Up to 14 bit	Up to 14 bit	Up to 14 bit	Up to 14 bit	Up to 14 bit
Resolution	Up to 16 bit	Up to 16 bit	Up to 16 bit	Up to 16 bit	Up to 16 bit
Accuracy	±0.022°	±0.022°	±0.022°	±0.022°	±0.022°
Flange Size in mm [in]	58 [2.28]	58 [2.28]	58 [2.28]	58 [2.28]	58 [2.28]
Flange Type	Clamp, Synchro, Blind Hollow	Clamp, Synchro, Blind Hollow	Clamp, Synchro, Blind Hollow	Clamp, Synchro, Blind Hollow	Clamp, Synchro, Blind Hollow
Shaft Diameters	From 6 to 15	From 6 to 15	From 6 to 15	From 6 to 15	From 6 to 15
in mm [in]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]
Material Flange /	Aluminum or	Aluminum or	Aluminum or	Aluminum or	Aluminum or
Housing	Stainless Steel /	Stainless Steel /	Stainless Steel /	Stainless Steel /	Stainless Steel /
	Steel	Steel	Steel	Steel	Steel
RPM / Radial Shaft Load in N	Max. 12000 / 110	Max. 12000 / 110	Max. 12000 / 110	Max. 12000 / 110	Max. 12000 / 110
Shock /	100 g /	100 g /	100 g /	100 g /	100 g /
Vibration <sup>1</sup>	10 g	10 g	10 g	10 g	10 g
Temperature	-40 to +85	-40 to +85	-40 to +85	-40 to +85	-40 to +85
in °C [°F] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /
Humidity	98 %	98 %	98 %	98 %	98 %
Connection	Connector	Connector	Connector	Connector	Connector
Supply Voltage	10 to 30 V	10 to 30 V	10 to 30 V	10 to 30 V	10 to 30 V
Certificate	UL, CE	UL, CE	UL, CE	UL, CE	UL, CE
Туре	OCD	OCD	OCD	OCD	OCD

<sup>1</sup> Based on (EN 60068-2-27) / (EN 60068-2-6)

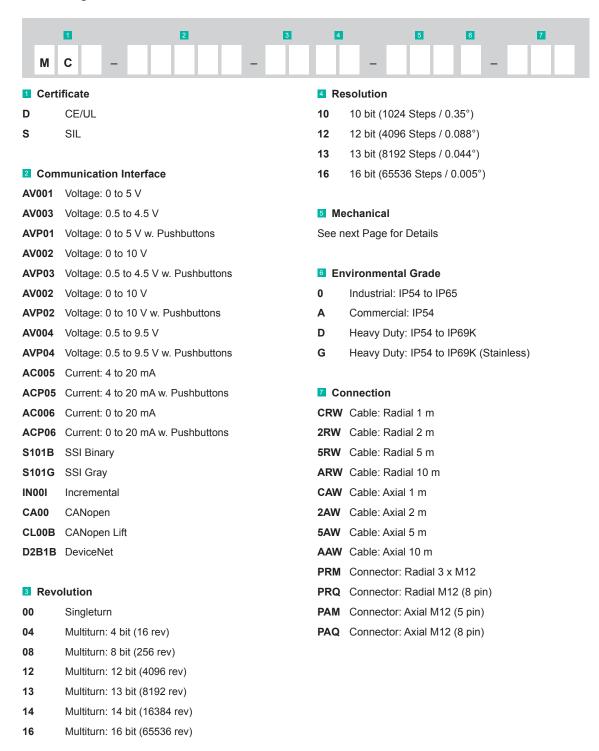
## **Explosion Proof and Safety-Rated Encoders**



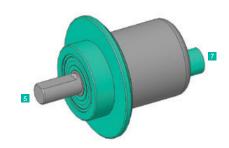
Highlights	ATEX rated bus Encoder	ATEX rated SSI Encoder	ATEX rated Ethernet Encoder	SIL CL 2 rated compact Encoder	SIL CL 3 rated precise Encoder
Protection Class	Up to IP67	Up to IP67	Up to IP67	Up to IP67	Up to IP67
Communication	PROFIBUS,	SSI	EtherNet/IP,	CANSafe	CANSafe
Interface	CANopen,		PROFINET,	(EN50325-5)	(EN50325-5)
	DeviceNet		Modbus TCP		
Technology	Optical	Optical	Optical	Magnetic	Optical
Revolutions	Up to 14 bit	Up to 14 bit	Up to 14 bit	Singleturn	Up to 14 bit
Resolution	Up to 16 bit	Up to 16 bit	Up to 16 bit	Up to 14 bit	Up to 16 bit
Accuracy	±0.022°	±0.022°	±0.022°	±1.8° (safe)	±0.35° (safe)
Flange Size in	78 [3.07]	78 [3.07]	78 [3.07]	25 [0.98]	58 [2.28]
mm [in]				58 [2.28]	
Flange Type	Clamp, Blind	Clamp, Blind	Clamp, Blind	Synchro	Clamp, Blind
	Hollow, Synchro	Hollow, Synchro	Hollow, Synchro		Hollow, Synchro
Shaft Diameters	Shaft 10 [0.39] /	Shaft 10 [0.39] /	Shaft 10 [0.39] /	6 [0.24]	From 6 to 15
in mm [in]	Hub 14 [0.55]	Hub 14 [0.55]	Hub 14 [0.55]	10 [0.39]	[0.24 to 0.59]
Material Flange /	Aluminum or	Aluminum or	Aluminum or	Aluminum /	Aluminum /
Housing	Stainless Steel	Stainless Steel	Stainless Steel	Steel	Steel
RPM /	Max. 3000 /	Max. 3000 /	Max. 3000 /	Application	Max. 6000 /
Radial Shaft	50	50	50	Dependent	110
Load in N					
Shock /	100 g /	100 g /	100 g /	100 g /	100 g /
Vibration <sup>1</sup>	10 g	10 g	10 g	10 g	10 g
Temperature	-40 to +75	-40 to +75	-40 to +75	-40 to +75	-30 to +70
in °C [°F] /	[-40 to +167] /	[-40 to +167] /	[-40 to +167] /	[-40 to +167] /	[-22 to +158] /
Humidity	98 %	98 %	98 %	98 %	98 %
Connection	Connection Cap	Connection Cap	Cable	Cable	Connector /
	with Cable Gland	with Cable Gland			Connection Cap
Supply Voltage	10 to 30 V	4.5 to 30 V	10 to 30 V	9 to 35 V	12 to 30 V
Certificate	ATEX/IECEx	ATEX/IECEx	ATEX/IECEx	SIL CL 2 and PI d	SIL CL 3 and PI e
Type	OCE/M-	OCE/M-	OCE/M-	MCS-	OCS-

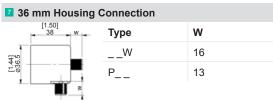
<sup>1</sup> Based on (EN 60068-2-27) / (EN 60068-2-6)

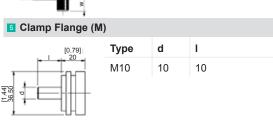
## **IXARC Magnetic Encoder**

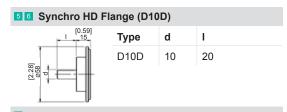


## Mechanical Interface and Connection Type: Magnetic Encoder - IXARC











Blind Hollow Flange (A06)						
	0.531] 13.50	Туре	d	I min / max		
[1.929] 049 [1.437] 036.50	Imin/Imax	A06	6	11 / 14		
5 Synchro F	lange (I	R)				
וַן	0.72]	Type	d	1		

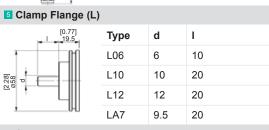
5 Synchro Flange (R)						
	[0.72] ~18.2	Туре	d	1		
I min / I max	R06	6	10			
[1.91] 48.60		R10	10	12		

All measurement in mm

7 42 mm Housing Connection					
[2.04] 51.8 w	Туре	w			
[1.50] ø38.2	W	15			
E.83	P	10			

5 Synchro HD Stainless Steel Flange (G10G)						
I [0.52]	Туре	d	1			
(1.65) 0.42 d	G10G	10	20			

58 mm Housing Connection							
[1.70] 43.2 - w	Туре	W					
(2.31) 858.6	W	20					
923	P	13					
(E)							



5 Synchro Flange (Y)								
[0.53] _13.5_ I	Туре	d	I					
1	Y06	6	10					
(2.28) 958 9	Y10	10	20					
_ ,	Y12	12	20					
Blind Hollow Flange (H)								

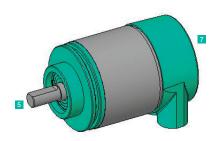
5 Blind Hollow Flange (H)								
		~28.40 I min / I max	Туре	d	I min / max			
Ī	7.20 7.20 9.88.5 9.88.5	H06	6	15 / 30				
[2.83] 72		H08	8	15 / 30				
۱ ٔ			H12	12	15 / 30			
ļ	1 1 2 2		H14	14	15 / 30			
			H15	15	15 / 30			

21

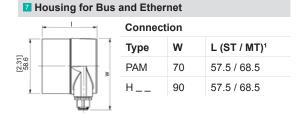
## **IXARC Optical Encoder**

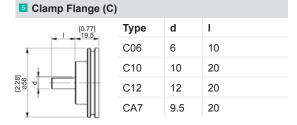
	1		2			3	1	4			5		6			7	
0	с –	Т	Т	П		П		Т		П	Т			_			
								E Ma	abaniaa		-						
	ificate		Resolut						chanica ext Page		ataile						
D	CE/UL	12		(4096 S	•		,	366 II	ext i age	, IOI De	Stalls						
E	Ex Oil/ Gas	13	13 bit	(8192 S	Steps /	0.044°	,	6 Fn	vironme	ntal G	rado						
M	Ex Mining	16	16 bit	(65536	Steps	/ 0.005	5°)	0	Industri								
S	SIL							S	Industri								
								V	Industri				Stai	nless	Stee	el)	
2 Com	munication In	terfa	ce					Н	Heavy I			•				,	
PP00B	Parallel Binary	y					,	w	Explosi	•				less (	Steel	)	
PP00G	Parallel Gray											,				,	
P100B	Parallel Prese	t bina	ıry					7 Co	nnectio	n							
P100G	Parallel Prese	t Gra	y					CRW	Cable: I	Radial	1 m						
S101B	SSI Binary							2RW	Cable:	Radial	2 m						
S401B	SSI Binary w.	Push	buttons					ARW	Cable:	Radial	10 m	ı					
S101G	SSI Gray							CAW	Cable:	Axial 1	m						
S401G	SSI Gray w. F	Pushb	uttons				:	2AW	Cable:	Axial 2	m						
	SSI+Incremer			A/B/Z (F	RS-422	<b>'</b> )		AAW	Cable:	Axial 1	0 m						
	SSI+Incremer		•	,				PRM	Connec	ctor: ra	dial 3	x M1	12 Et	hern	et		
	SSI+Incremer		•	,		•		PRL	Connec	tor: rac	dial M	123 (1	2 pir	1)			
	SSI+Incremer		•	,				PRP	Connec	tor: rac	dial M	123 (1	6 pir	1)			
	Profibus DP	ilai C	nay ' A	D/Z (I C	1311-1 U	")		PRT	Connec	tor: rac	dial M	127 (2	6 pir	1)			
								PRM	Connec	tor: rac	dial M	112 (5	pin)				
	CANopen							PRM	Connec	tor: rac	dial 2	x M1	2 Mc	dbus	i		
	CANopen Lift								Connec								
	DeviceNet							PRI	Connec				•	. ,			
	Interbus								Connec			•	. ,				
EIB1B		)							Connec			`	•				
EEA0B	EtherNet/IP								Connec			•					
	POWERLINK							PAM	Connec								
EC00B	EtherCAT							PAQ H3P	Connec				' '	nde			
EM00B	Modbus/TCP							nse H1B	Connec						or		
								H72	Connec		•						
3 Revo	olution							п/2 Н2В	Connec								
00	Singleturn							H2M	Connec							s	
08	Multiturn: 8 bit	t (256	rev)					H1C	Connec								
12	Multiturn: 12 b	oit (40	96 rev)						Connec		•						
13	Multiturn: 13 b	oit (81	92 rev)					HFZ	Connec		•			ands	(for (	OCE	/ OCM
14	Multiturn: 14 b	oit (16	384 rev)	ı				HFE	Connec		•		•		`		
16	Multiturn: 16 b	•	,					HFG	Connec		•		•		`		

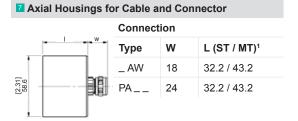
## Mechanical Interface and Connection Types: Optical Encoder - IXARC

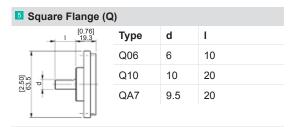


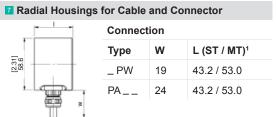
# Type d T08 8 T10 10 T12 12

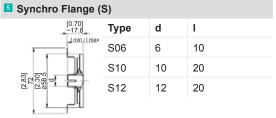


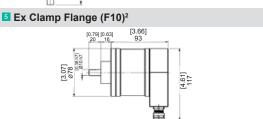


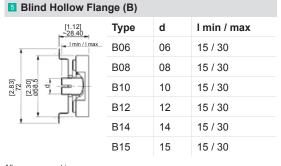










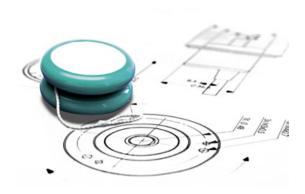


70.8 87.8 12.8 12.8 13.8 14.1 17.1 

5 Ex Blind Hollow Flange (E14)2

1 ST singleturn, MT multiturn 2 Available for OCE/M Types

#### TECHNOLOGY LINEAR SENSORS - LINARIX



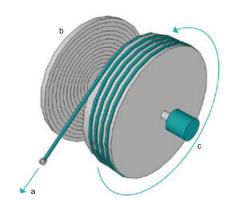
POSITAL's LINARIX draw wire sensors measure linear motion by displacing a retractable steel wire (a) wound around a cable drum (b) that actuates the rotary encoder (c) coupled to it. The encoder in return provides a proportional output. Measurements are highly accurate, reliable and the systems have very long lifetimes. The LINARIX line offers a wide range of measurement lengths ranging from 1 m to 15 m and also provides position output in almost all available industrial interfaces both analog and digital.

Compared to the conventional linear pots and linear measurement systems using multiple gears and encoders, the LINARIX line of sensors are more durable and can directly replace them, additionally, avoiding the common problems of slippage, wear and



tear damage. The draw wire sensors from POSITAL provide extremely precise measurements because of the inherent accuracy of the encoders and the rugged construction ensures reliable performance even under extreme conditions.

The POSITAL product offering has been categorized based on robustness and length giving the customer maximum selectability based on their respective application.





# PRODUCT OVERVIEW LINEAR SENSORS - LINARIX

Draw Wires for	Commercial Use	Î			
·	William	William of the Control of the Contro	3	. 6	
Measuring Range in m [in]	1.25 [49]	1.25 [49]	2.10 [83]	3.00 [118]	1.74 [69]
Communication Interfaces <sup>1</sup>	Analog, SSI, CANopen, DeviceNet	Analog, SSI, CANopen, DeviceNet	Analog, SSI, CANopen, DeviceNet	Analog, SSI, CANopen, DeviceNet	Analog, SSI, CANopen, DeviceNet
Accuracy in [±FSO%]	0.05	0.04	0.05	0.04	0.02
Wire Material	Coated Polyamide Stainless Steel	Nylon Coated Stainless Steel	Coated Polyamide Stainless Steel	Nylon Coated Stainless Steel	Coated Polyamide Stainless Steel
Wire Diameter in mm	0.36	0.48	0.45	0.48	0.45
Draw Wire Housing Material	Plastic	Anodized Aluminum Frame, Polycarbonate Spring Housing	Plastic	Anodized Aluminum Frame, Polycarbonate Spring Housing	Aluminum
Operating Temperature in °C [°F]	-20 to 80 [-4 to 176]	-40 to 94 [-40 to 201]	-20 to 80 [-4 to 176]	-40 to 94 [-40 to 201]	-20 to 80 [-4 to 176]
Max. Extension Force in N	1.50	2.34	5.00	3.90	5.00
Min. Retraction Force in N	1.00	1.26	3.50	2.10	3.50
Digital Resolu- tion² in μm	31	24	52	49	36
Drum Circumfe- rence in mm [in]	125 [4.9]	100 [3.9]	215 [8.5]	200 [7.9]	149 [5.9]
Type Key	LNC	LAC	LMC	LBC	LPC

<sup>1</sup> Other interfaces available on request

<sup>2</sup> Based on an encoder with 12 Bit Resolution

# PRODUCT OVERVIEW LINEAR SENSORS - LINARIX



Measuring Range in m [in]	2 [79]	3 [118]	6 [236]
Communication Interfaces <sup>1</sup>	Analog, SSI,	Analog, SSI,	Analog, SSI,
	CANopen, DeviceNet	CANopen, DeviceNet	CANopen, DeviceNet
Accuracy in [±FSO%]	0.02	0.01	0.01
Wire Material	Plastic Coated	Plastic Coated	Stainless Steel
	Stainless Steel	Stainless Steel	
Wire Diameter in mm	0.45	0.87	0.54
Draw wire Housing	Zinc Die-Cast	Zinc Die-Cast	Aluminum / Plastic
Material			
Operating Temperature in	-10 to 80	-40 to 80	-20 to 80
°C [°F]	[14 to 176]	[-40 to 176]	[-4 to 176]
Max. Extension Force in N	2	3	8
Min. Retraction Force in N	1.2	2.5	3.0
Digital Resolution² in μm	24	49	40
Drum Circumference in	100 [3.9]	200 [7.9]	200 [7.9]
mm [in]			
Type Key	LCN	LDN	LEN

<sup>1</sup> Other interfaces available on request

<sup>2</sup> Based on an encoder with 12 Bit Resolution

## PRODUCT OVERVIEW LINEAR SENSORS - LINARIX

## **Draw Wires for Heavy Duty Use**



Measuring Range in m [in]	3.00 [118]	5.00 [197]	5.08 [200]	10.00 [394]	10.16 [400]
Communication	Analog, SSI,	Analog, SSI,	Analog, SSI,	Analog, SSI,	Analog, SSI,
Interfaces1	CANopen,	CANopen,	CANopen,	CANopen,	CANopen,
	DeviceNet	DeviceNet	DeviceNet	DeviceNet	DeviceNet
Accuracy	0.02	0.02	0.02	0.01	0.02
in [±FSO%]					
Wire Material	Coated Polyamide	Nylon Coated	Nylon Coated	Nylon Coated	Nylon Coated
	Stainless Steel	Stainless Steel	Stainless Steel	Stainless Steel	Stainless Steel
Wire Diameter	0.80	1.00	0.86	1.00	0.86
in mm					
Draw wire	Aluminum	Aluminum	Powder painted	Aluminum	Powder painted
Housing Material			Aluminum		Aluminum
Operating	-20 to 80	-20 to 80	-40 to 90	-20 to 80	-40 to 90
Operating Temperature	-20 to 80 [-4 to 176]	-20 to 80 [-4 to 176]	-40 to 90 [-40 to 194]	-20 to 80 [-4 to 176]	-40 to 90 [-40 to 194]
Temperature					
Temperature in °C [°F]	[-4 to 176]	[-4 to 176]	[-40 to 194]	[-4 to 176]	[-40 to 194]
Temperature in °C [°F] Max. Extension	[-4 to 176]	[-4 to 176]	[-40 to 194]	[-4 to 176]	[-40 to 194]
Temperature in °C [°F] Max. Extension Force in N	[-4 to 176]	[-4 to 176]	[-40 to 194] 6.5	[-4 to 176] 21.0	[-40 to 194]
Temperature in °C [°F] Max. Extension Force in N Min. Retraction	[-4 to 176]	[-4 to 176]	[-40 to 194] 6.5	[-4 to 176] 21.0	[-40 to 194]
Temperature in °C [°F] Max. Extension Force in N Min. Retraction Force in N	[-4 to 176] 9.0 5.5	[-4 to 176] 16.0 4.0	[-40 to 194] 6.5 3.5	[-4 to 176] 21.0 8.0	[-40 to 194] 6.5 3.5
Temperature in °C [°F] Max. Extension Force in N Min. Retraction Force in N Digital Reso-	[-4 to 176] 9.0 5.5	[-4 to 176] 16.0 4.0	[-40 to 194] 6.5 3.5	[-4 to 176] 21.0 8.0	[-40 to 194] 6.5 3.5
Temperature in °C [°F] Max. Extension Force in N Min. Retraction Force in N Digital Reso- lution² in µm	[-4 to 176] 9.0 5.5 63	[-4 to 176] 16.0 4.0	[-40 to 194] 6.5 3.5	[-4 to 176] 21.0 8.0	[-40 to 194] 6.5 3.5

<sup>1</sup> Other interfaces available on request

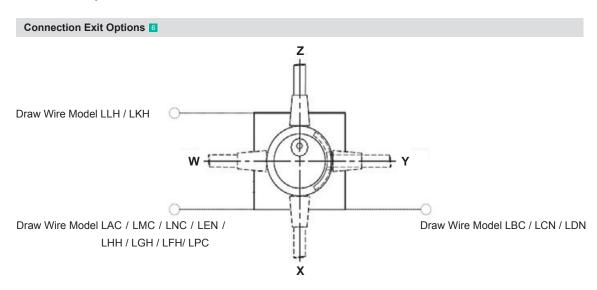
Please refer to the product finder on our website for all possible combinations.

<sup>2</sup> Based on an encoder with 12 Bit Resolution

## Linear Sensors – LINARIX

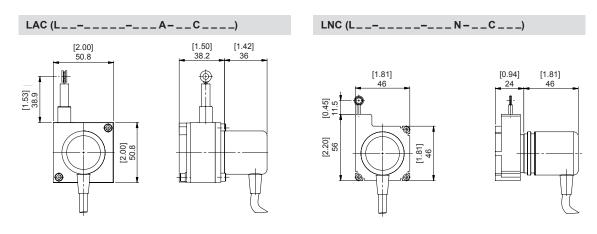
	1			2		3	4	5		6	7	8	g	1	
	L	0 -	П		_		П		_				Т	Τ	
1 Tec	hnology	,					4 En	coder F	Resolu	ıtion					
W	Draw W	ire Only					00	Draw V	Vire O	nly					
D	Optic (D	Diode)					D2	12 bit							
М	Magnet	ic					D3	13 bit							
							D4	16 bit							
2 Cor	nmunica	ation Interfa	ce												
00000	Draw '	Wire Only						aw Wire		••					
AV001	Voltag	e: 0 to 5 V					See n	ext Page	e for L	etails	S				
AVP01	Voltag	e: 0 to 5 V w	. Pushbu	ıttons			C C	nnootio	n Evi	t Ont	iono				
AV002	Voltag	e: 0 to 10 V						onnection ext Page							
AVP02	. Voltag	e: 0 to 10 V	w. Pushb	outtons			366 H	iekt i agt	e ioi L	Clan	5				
AC005	Currer	nt: 4 to 20 m.	Α				7 En	vironmo	ental	Grad	e En	coder			
ACP05	5 Currer	nt: 4 to 20 m.	A w. Pusl	hbuttons			Α	Comme							
P100B	Paralle	el Binary with	Preset				s	Industri	ial IP5	64 to I	P67				
P100G	Paralle	el Gray with	Preset				0	Industri	ial IP5	64 to I	P65				
S101B	SSI Bi	inary													
S101G	SSIG	ray					8 En	vironm	ental	Grad	e Dra	w Wire			
S5xxB	SSI Bi	inary + Incre	mental A	/B/Z (RS-	-422)		С	Comme	ercial						
S6xxB	SSI Bi	nary + Incre	mental A	/B/Z (Pus	sh-Pull)		N	Industr	ial						
S5xxG	SSIG	ray + Increm	ental A/E	3/Z (RS-4	22)		Н	Heavy	Duty						
S6xxG	SSIG	ray + Increm	ental A/E	B/Z (Push	-Pull)										
N00I	Incren	nental						onnectio							
OPC1E	3 Profib	us DP					000	Draw V		•					
CAA1E	B CANo	pen						1 m P							
	3 CANo							10 m P							
	B Device						CAW	1 m P							
BA1B	Interb	us						M23 12							
EIB1B	PROF	INET IO						M23 16	•						
EEA0E	B Ether	Net/IP					PRT	M26 26							
	B POWE						PRM	M12 5	•						
	3 Modbi							2 x M1				Exit			
							PRQ	M12 8	pin - F	Radia	Exit				
3 Mea	asureme	ent Range					PAL	M23 12	2 pin -	Axial	Exit				
1	1 m						PAP	M23 16	in -	Axial	Exit				
2	2 m						PAM	M12 5	pin - A	xial E	Exit				
3	3 m						PAQ	M12 8	pin - A	xial E	Exit				
5	5 m						Н3Р	M12 Ca							
6	6 m							M12 C							
о А	10 m						H2B								
~	10 111						H1C	M23 C	onnec	tor x	1				

## **Mechanical Options LINARIX Linear Sensors**



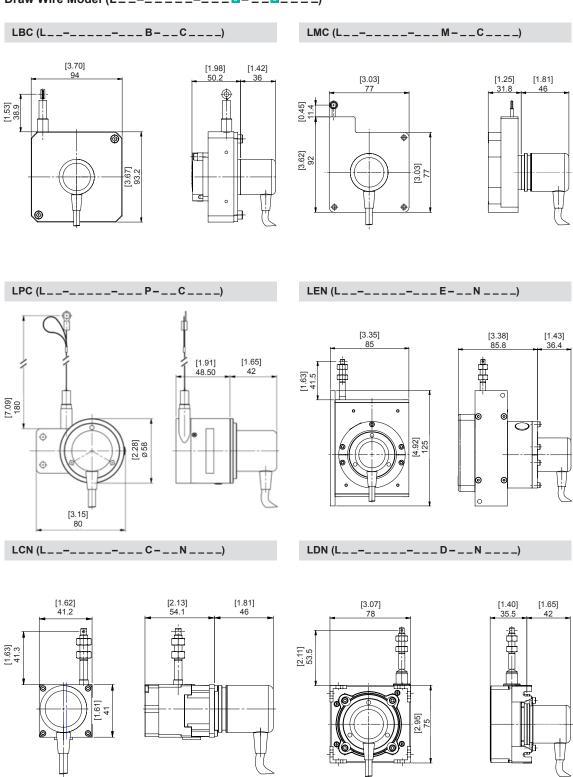
Connection Exit selected based on Draw Wire Model 5. When Draw Wire Model is "Draw Wire Only" then Connection Exit Option 5 is 0.

## 



## **Mechanical Options LINARIX Linear Sensors**

Draw Wire Model (L\_\_-\_\_\_\_\_5-\_\_5-\_\_5-\_\_\_5-\_\_\_)

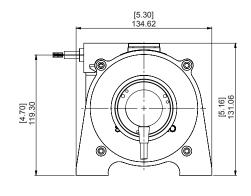


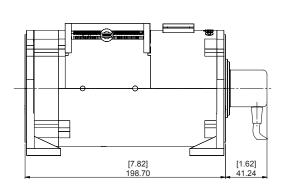
30

## **Mechanical Options LINARIX Linear Sensors**

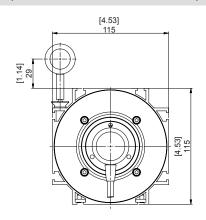
## Draw Wire Model (L\_\_-\_\_\_\_5-\_\_5-\_\_5-\_\_)

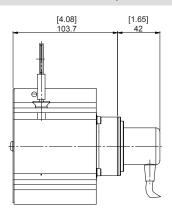
## LLH (L\_\_\_\_\_\_ K-\_H\_\_\_) and LKH (L\_\_-\_\_\_ K-\_H \_\_\_)



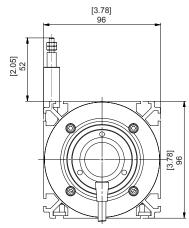


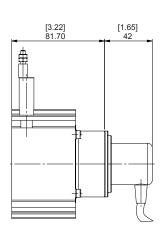
## LGH (L\_\_\_\_\_ H\_\_\_) and LHH (L\_\_\_\_ H\_\_\_)



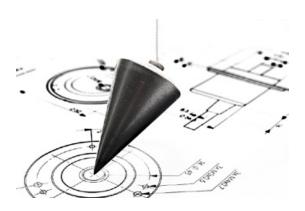


## LFH (L\_\_-\_\_ F-\_\_H \_\_\_)





#### TECHNOLOGY INCLINOMETER - TILTIX



POSITAL's TILTIX Inclinometers are based on highly dynamic MEMS (Micro-Electro-Mechanical Systems) technology and on high precision Fluid Cell Technology.

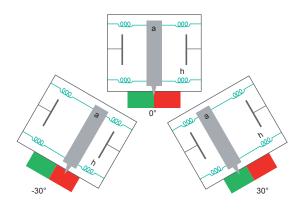
#### **MEMS**

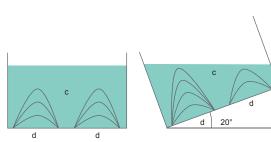
In MEMS devices, a 'micro mass' (a) is suspended in a flexible support structure (h). Any movement will induce a displacement of the mass, which will result in a change of the capacitance between the mass and the holding structure. Changes of inclination are calculated from these measured capacitance changes. These inclinometers have a measurement range of ±80° in two axes or 360° in one axis. The devices can withstand shock and vibration loadings of up to100 g as per EN 60068-2-27. They offer excellent dynamic response.



#### Fluid Cell

A sensor cell is partially filled with an electrolytic liquid (c); the walls are covered with electrodes (d). As the senor tilts, the level of fluid covering the electrodes changes. This results in the increase or decrease of conductivity between a pair of electrodes. With measure of the conductivity between the electrodes, one can calculate the tilt angle. Fluid Cells are capable of measuring inclinations of up to  $\pm 30^{\circ}$  with a very high level of precision. The natural damping of liquids makes these inclinometers precise as well as stable.





## PRODUCT OVERVIEW INCLINOMETER - TILTIX

#### **Inclinometer for Industrial Environments**



<sup>1</sup> Based on (EN 60068-2-27) / (EN 60068-2-6)

Please refer to the product finder on our website for all possible combinations.

# PRODUCT OVERVIEW INCLINOMETER – TILTIX

## **Inclinometer for Tough Environments**





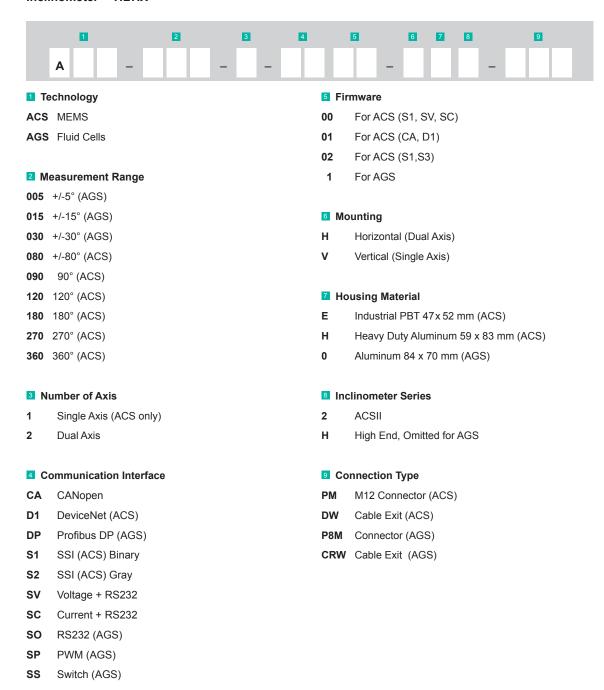


Highlights	Rugged Programmable	Rugged SSI Inclinometer	Rugged Bus
	Analog Inclinometer		Inclinometer
Protection Class	Up to IP69K / IP68	Up to IP69K / IP68	Up to IP69K / IP68
Interfaces	Analog	SSI	CANopen,
	Voltage or Current		DeviceNet,
			SAE J1939
Technology	MEMS	MEMS	MEMS
Max Measurement Range	2-axis ±80° /	1-axis 0° to 360°	2-axis ±80° /
	1-axis 0 to 360°		1-axis 0 to 360°
Resolution	0.01°	0.04°	0.01°
Accuracy	0.1°	0.1°	0.1°
Material Housing	Aluminum	Aluminum	Aluminum
Shock /	100 g /	100 g /	100 g /
Vibration <sup>1</sup>	20 g	20 g	20 g
Operating Temperature	-40 to +85	-40 to +85	-40 to +85
in °C [°F]	[-40 to 185]	[-40 to 185]	[-40 to 185]
Supply Voltage	10 to 30 V	5 to 30 V	10 to 30 V
Connection	Cable /	Cable /	Cable /
	Connector (M12)	Connector (M12)	Connector (M12)
Certificates	CE	CE	CE
Туре	ACSH2	ACSS1H2	ACSCA/D1H2

<sup>1</sup> Based on (EN 60068-2-27) / (EN 60068-2-6)

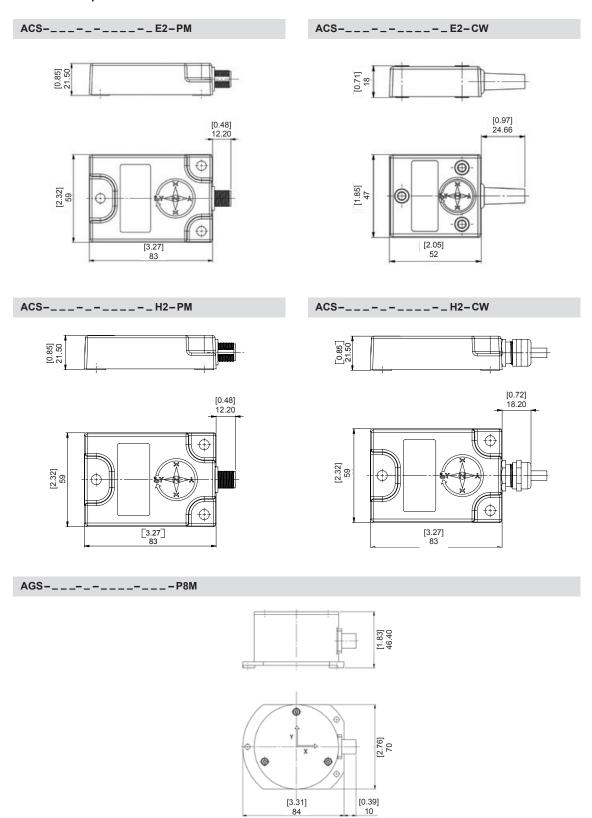
## PRODUCT SELECTION GUIDE INCLINOMETER - TILTIX

#### Inclinometer - TILTIX



## PRODUCT SELECTION GUIDE INCLINOMETER - TILTIX

## **Mechanical Options TILTIX Inclinometer**



# PRODUCT OVERVIEW ACCESSORIES

# **Mounting Options: Couplings and Reducing Adapters**



Product	Reducing Adapter	Couplings	Couplings	Couplings
Diameters /	15 to 12 /	6 to 6, 6 to 10,	6 to 6, 6 to 10,	6 to 6, 6 to 10,
Sizes in mm	15 to 10	10 to 10	10 to 10	10 to 10
Types or Material	Stainless Steel,	Bellow	Disc	Jaw
	Aluminum			



Product	Flange Adapters	Tethers and Clamp Rings	Clamp Discs
Features	MGY58 and Flange	Various torque supports	Clamp discs to mount
	Adapters	and clamping discs	encoders onto a surface
Material	Aluminum, Plastics	Aluminum, Stainless Steel	Aluminum

# PRODUCT OVERVIEW ACCESSORIES

## **Electrical Connections and Interface Options**

## **Connectors and Cordsets**











Standards	M12	M23	M27	M12 Assembly	M23 Assembly,
					M27 Assembly
Lengths	_	-	-	2, 5, 10	2, 5, 10
Pins /	4 pin D,	9, 12, 16	26	4 pin D,	9, 12, 16, 26
Cables	5 pin A,			5 pin A,	
	8 pin A			8 pin A	
Material of Cable	_	_	_	PUR / PVC	PUR / PVC
Material	Metal	Metal	Metal	PBT	Metal
of Connector				Metal	
Termination	_	-	-	Open Ends /	Open Ends
				RJ45	
Protection Type	IP67	IP67	IP67	IP69K	IP67

## **Configuration and Interface Modules**





Product	SSI2USB Module	Voltage Panel Display
Features	<ul> <li>Easy interface of SSI device</li> </ul>	<ul> <li>Measures voltage from 0 to 40V d.c</li> </ul>
	to USB port of PC	<ul> <li>2.4" color TFT screen</li> </ul>
	<ul> <li>Graphical User Interface</li> </ul>	<ul> <li>Use PanelPilot software, to setup</li> </ul>
	to view and store SSI Data	and customize the display
	<ul> <li>Power Supply to SSI device</li> </ul>	Programmable via the USB interface
	(max 12 Volts) using USB Port	<ul> <li>Simple panel mounting solution</li> </ul>
	Three independent tri-state outputs	Wide operating voltage
	<ul> <li>Could be used as a Virtual Com</li> </ul>	of 4V to 30V d.c.
	port device	

# **GLOSSARY**

Analog	A common standard with either a voltage or a current output		
ATEX / IECEx	ATEX and IECEx norms define essential requirements for equipment and		
	protective systems intended for use in potentially explosive atmospheres		
CANopen	CANopen is a fieldbus protocol using CAN networks		
CANopen Lift	CANopen Lift is a fieldbus protocol for elevator applications		
CE	With the CE marking POSITAL declares that the product conforms with		
	essential requirements of the applicable EC directives		
DeviceNet	DeviceNet is a fieldbus system based on CAN networks and CIP protocol,		
	managed by ODVA, widely used in factory automation and available on		
	many PLCs		
EtherNet/IP	EtherNet/IP is an industrial communication protocol developed by Rockwell		
	Automation and managed by ODVA. It is based on CIP and TCP/IP protocol		
ETHERNET POWERLINK	Ethernet Powerlink is a real-time communication system based on Ethernet		
	networks and managed by EPSG		
Interbus	Interbus is a fieldbus technology developed by Phoenix Contact		
IP54	Protected against dust and contact and splashed water from all directions		
IP65	Dust and Contact proof and protection against powerful water jets		
IP67	Dust and Contact proof and protection against temporary immersion		
	upto 1 m		
IP68	Dust and Contact proof and protection against water pressure		
IP69K	Dust and Contact proof and protected against high pressure,		
	high temperature wash down applications		
Modbus	Modbus is a serial protocol managed by the Modbus Organization		
Parallel	All bits of the position output are transferred simultaneously using one line		
	for each bit		
PROFIBUS	Profibus is available on many PLCs and one of the most common fieldbus		
	technologies in factory automation and other areas. It is based on RS485.		
	There are different versions of Profibus and different device profiles		
PROFINET	Profinet is an Industrial Ethernet standard from		
	"Profibus&ProfiNet International" designed for automation		
SAE J1939	SAE J1939 is a fieldbus standard used for communication by the car and		
	heavy-duty truck industry		
SIL	SIL (Safety Integrity Level) is defined as a relative level of risk-reduction		
	provided by a safety function. In accordance with the requirements of IEC		
	61508/EN 62061, PL e and Cat.4 according to EN ISO 13849-1		
SSI	SSI is a widely used serial interface with point-to-point connection between		
	PLC/Master and encoder. It is based on the RS422 standard		
UL	UL (Underwriters Laboratories) is a US based consulting and certification		
	company providing safety standards for electrical devices. UL marking		
	confirms the compliance with applicable UL safety standards		

